

A Mobile System for Assessment of Physiological Response to Posture Transitions

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Abstract— *Posture changes initiate a dynamic physiological response that can be used as an indicator of the overall health status. We introduce an inconspicuous mobile wellness monitoring system (imWell) that continuously assesses the dynamic physiological response to posture transitions during activities of daily living. imWell utilizes a Zephyr BioHarness 3 physiological monitor that continually reports heart activity and physical activity via Bluetooth to a personal device (e.g. smartphone). The personal device processes the reported activity data in real-time to recognize posture transitions from the accelerometer data and to characterize dynamic heart response to posture changes. It annotates, logs, and uploads the heart activity data to our mHealth server. In this paper we present algorithms for detection of posture transitions and heart activity characterization during a sit-to-stand transition. The proposed system was tested on seven healthy subjects performing a predefined protocol. The total average and standard deviation for sit-to-stand transition time is 2.7 ± 0.69 s, resulting in the change of heart rate of 27.36 ± 9.30 bpm (from 63.3 ± 9.02 bpm to 90.66 ± 10.09 bpm).*

I. INTRODUCTION

Cardiovascular diseases represent the leading cause of death in the United States. The current practices in monitoring health status are expensive, often insufficient, and limited to monitoring in healthcare facilities. Patients usually consult cardiologists only after experiencing first symptoms of deteriorating cardiac status. Cardiologists usually administer exercise stress test to assess cardiac status. Standard stress tests are bike or treadmill exercise supervised by a doctor or a trained technician to determine the level of exercise a patient can tolerate. The tests are usually followed by prescribed therapeutic lifestyle changes including modifications of diet and development of an exercise program with a follow-up after several months. However, the clinicians do not have tools to assess the patients' progress and their compliance to the prescribed therapies. Patients and healthy users lack tools to monitor their own cardiac status and to manage healthy lifestyle.

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Emergence and proliferation of lightweight and wearable physiological sensors enable the design of digital assistants that are capable of continual sensing and processing of cardiac activity and physical activity. A number of new consumer-grade devices for health and wellness monitoring has been introduced [1], [2]. Examples include pedometers that count number of steps and calories, and more sophisticated devices, such as heart and metabolic monitors. On the other side, an increasing number of users actively monitor their own health and fitness status [3]. The availability of affordable wearable devices and their consumer acceptance create new opportunities for individual users and healthcare professionals.

Posture changes, such as transitions from sitting to standing, induce a physiological response that can be used to characterize fitness status of the user. Figure 1(b) shows heart rate recorded during a posture transition from sitting to standing for a healthy subject (blue line) and a subject with cardiac condition (red line). The heart rate in the healthy subject quickly increases as a response to the physical activity and then returns to a level that corresponds to the new homeostasis, whereas the heart rate in the cardiac patient increases barely and slowly.

We hypothesize that characterizing this dynamic response, including a change in the heart rate and time to reach the maximum, can be used to indicate the subject's cardiac status and overall wellness. Long term monitoring of cardiac health and physical activity during activities of daily living can provide an indication of short term and long term changes of the cardiac status and fitness. The goal of this paper is to develop an inconspicuous wearable cardiac and wellness assistant, called *imWell* (*inconspicuous mobile Wellness*), for efficient unobtrusive monitoring of physical activity, cardiac health, and overall physical wellness.

The *imWell* system continually records interbeat intervals and processes accelerometer data to recognize posture transitions (Section III.A). For detected sit-to-stand posture transitions the system characterizes dynamic heart response by extracting transition timestamp, duration, heart rate before and after transition, and the time needed to reach the maximum heart rate from the beginning of the transition (Section III.B). This way we treat each sit-to-stand posture change, which happens dozens of times per day, as a mini "exercise stress test". Analyzing the results of these tests over a long period of time, we could assess a subject's cardiac status and fitness.

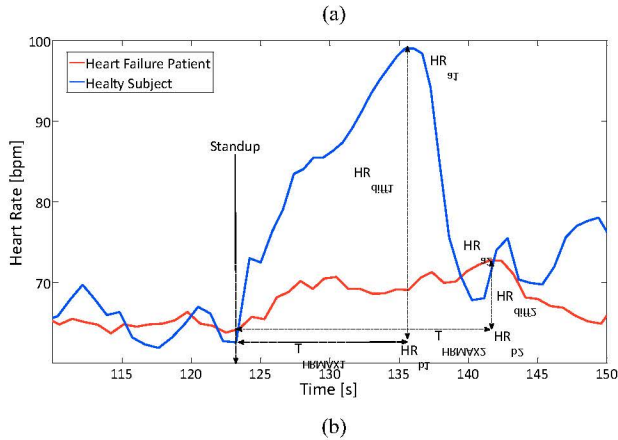


Figure 1. Modeling change of heart activity induced by transition from sitting to standing

Similar to a personal digital assistant that helps individuals manage day-to-day data needs, the *imWell* system serves as a personal assistant that helps individuals manage their cardiac health and physical wellness. Such a system can benefit: (a) *healthy subjects*, allowing them to track and manage the overall cardiac health status and physical fitness over long periods of time, (b) *cardiac rehabilitation patients*, allowing them to monitor and guide their rehabilitation and detect early deterioration of cardiac status; and (c) *physicians and healthcare professional*, allowing them to monitor patient's cardiac health status and to verify their compliance to prescribed lifestyle changes and exercises.

II. RELATED WORK

Recognition and quantification of human activities using small wearable sensors during activities of daily living has been increasingly used in many applications. Automatic activity recognition and quantification systems that utilize inertial sensors are proposed for long-term health and fitness monitoring [4], [5], assessing of mobility in elderly and people with Parkinson's disease [6]–[8], automatic fall detection [9], [10], and rehabilitation [11], [12]. Approaches for automatic activity recognition used by researchers vary in number, type, and placement of utilized sensors, as well as in processing of recorded signals. While some researchers used multiple sensors for automatic activity recognition [13]–[15] increasing number of projects use a single inertial sensor [16]–[19] usually placed on the chest.

One of the most challenging tasks in automatic activity recognition is detection and differentiation of posture transitions sit-to-stand and stand-to-sit. A number of researchers monitored angle of trunk tilt to detect possible posture changes by detecting situations when the angle exceeds certain threshold [16], [18]–[20]. Researchers used a

variety of approaches to differentiate aforementioned transitions. Godfrey et al. [19] used vertical velocity, Fleury et al. [20] used wavelet-based pattern recognition on accelerometer data and tilt angle, while Fuentes et al. [18] used angle and forward and vertical acceleration.

III. METHODS

Our system relies on a physiological monitor Zephyr BioHarness 3 to capture both inertial and physiological data (acceleration and RR-intervals). The monitor is placed in a chest belt worn by the user and communicates the data via Bluetooth to a personal device. The personal device (a) processes the signals to detect and timestamp transitions using the data from the accelerometer, (b) extracts, characterizes, and records dynamic heart response to sit-to-stand transitions, and (c) uploads the records to a mHealth server [21].

A. Posture Transition Detection

Figure 1(a) shows a user during a transition from sitting to standing and orientation of the Zephyr's inertial sensor, with vertical axis (x), lateral (y), and sagittal (z). The Zephyr monitor is mounted on a chest strap located under the subject's left arm. The inertial sensor samples and reports acceleration components A_x , A_y , and A_z with the sampling frequency of 50 Hz. When the user is standing still or sitting in the upright position we should observe $A_x = -1g$, $A_y = A_z = 0$, where g is the Earth gravity (9.81 m/s^2).

The first step in identifying possible posture transitions is to detect a change in the upper body angle relative to the upright position, θ , and a change in the acceleration vector magnitude, $AccMag$. The upper body angle is calculated as follows: $\theta = \arctan(A_z/A_x)$, where $\theta = 0$ degrees in the upright position as shown in Figure 1(a). The angle has a characteristic signature during posture transitions sit-to-stand and stand-to-sit. Figure 2(b) shows the angle during a sit-to-stand transition. We can identify 3 characteristic points in the angle signature – two purple circles mark the beginning (*BeginTransition*) and the end of the transition (*EndTransition*), and purple diamond marks the angle peak (*AnglePeak*).

To identify a possible posture transition we search for a segment where the angle rises above a certain threshold. However, the angle θ may include offsets caused by imperfect monitor placement and monitor's movements relative to the body. To eliminate the impact of the offsets we calculate the standard deviation of the angle θ on a sliding window of 1 second, $stdev(\theta)$, and use it to locate possible posture transitions. This signal is searched for maximums in segments that are above a certain threshold. Once we locate candidate segments we search for three characteristic points in the original angle (*BeginTransition*, *AnglePeak*, and *EndTransition*).

To estimate the level of physical activity we calculate the standard deviation of the acceleration vector magnitude on a sliding window of 1 second, $stdev(AccMag)$. The $stdev(AccMag)$ is used to distinguish between posture transitions and motion artifacts such as leaning

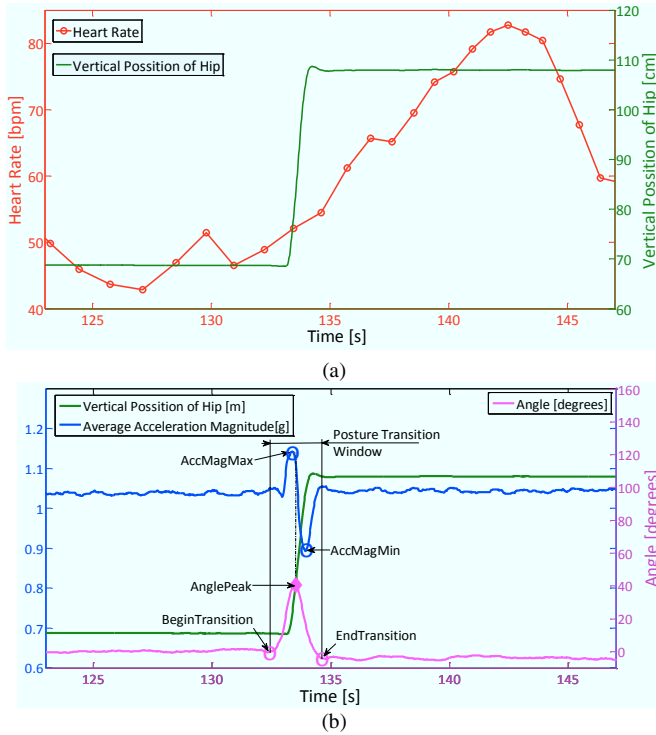


Figure 2. An example of physiological response during a transition from sitting to standing: a) real-time heart rate calculated from RR intervals and hip position; b) angle and magnitude calculated from accelerometer signals and hip position.

forward/backward/sideways in a chair. If the maximum $stdev(AccMag)$ in a candidate segment is higher than a certain threshold, we mark this segment as a true transition. In true transition segments, we search the acceleration vector magnitude for two characteristic points, marked by blue circles in Figure 2(b), representing the maximum and the minimum ($AccMagMax$, $AccMagMin$).

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sit2stand = 0
if (Time(AccMagMax) < Time(AccMagMin))
    sit2stand++
else
    sit2stand--
if ((Time(AccMagMax) - Time(BeginTransition)) <
    (Time(EndTransition) - Time(AccMagMax)))
    sit2stand++
else
    sit2stand--
if (Time(AccMagMax) < Time(AnglePeak))
    sit2stand++
else
    sit2stand--
if (sit2stand > 0) Transition=Sit-To-Stand
else
    Transition=Stand-To-Sit

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Figure 3. Algorithm for determining the type of posture transition.

The next step is to determine the type of the posture transition. In order to distinguish between the sit-to-stand and the stand-to-sit transitions, we employ multiple criteria that consider ordering of the characteristic points in time. The type of the transition is determined by a voting system described in Figure 3.

B. Dynamic Heart Response

inWell continually records the subject's heart activity. In addition, the dynamic heart response to a sit-to-stand posture transition is characterized in near real-time. The characterization is performed once the transition is detected and involves determining characteristic points as shown in Figure 1(b): (i) heart rate at the beginning of posture transition (HR_b), (ii) the maximum heart rate after the transition is performed (HR_a), and (iii) the timestamp of the maximum heart rate. From these parameters we calculate the heart rate difference (HR_{diff}) and the time needed to reach the maximum heart rate from the beginning of the transition (T_{HRMAX}). To find HR_a , we search for the maximum heart rate in a time window of 13 seconds after $EndTransition$. If it is detected at the end of this window, we continue the search for the maximum beyond this point in time, until the heart rate starts decreasing.

For each sit-to-stand transition we record the following parameters: (a) $Time(BeginTransition)$, (b) $T_{Transition} = Time(EndTransition) - Time(BeginTransition)$, (c) HR_a , HR_b , HR_{diff} , (d) T_{HRMAX} , (e) T_{SIT} , and (f) T_{STAND} , where T_{SIT} is the duration of sitting before the transition, and T_{STAND} is duration of standing still after the transition. T_{SIT} and T_{STAND} can help further characterize posture transitions: e.g., in analysis we would consider only transitions for which T_{SIT} is longer than a certain time period (e.g., 60 seconds) and T_{STAND} is longer than T_{HRMAX} .

IV. EXPERIMENTAL SETUP

We record signals during a series of cued posture transitions driven by our custom program [22]. The protocol includes (1) Quite sitting for 5 min, (2) Stand still for 30 sec, (3) Quite sitting for 2 min, (4) Stand still for 30 sec, (4) Sitting & working on computer for 1 min, (5) Walking for 30 sec, (6) Sitting and working on computer for 1 min, (7) Walking for 30 sec, (8) Sitting and working on computer for 1 min, (9) Walking for 30 sec, and (10) Sitting and working on computer for 1 min.

In addition, we record videos of experiments using the custom program that captures video and synchronizes with other measurements and the cues. The experiments with multiple participants were conducted in the Real-time Physiological Monitoring Lab [22] and Autonomous Tracking Optical Measurement (ATOM) Lab [23]. The ATOM lab allows accurate tracking of reflective markers using 33 Vicon T40 series IR cameras.

Our algorithms for detection and characterization of posture transitions rely exclusively on the data from the Zephyr monitor, and we use the Vicon system only for algorithm verification. The experiments in the ATOM lab allow us to accurately capture body movements during posture transitions and thus precisely determine the beginning and the end of each posture transition. The users wear the Zephyr BioHarness monitor and strategically placed reflective markers. The Vicon system records the absolute position of each marker with millimeter precision every 20 ms.

V. RESULTS, DISCUSSION, AND CONCLUSION

The inertial and heart activity data are collected on 7 healthy participants who performed the protocol described in the previous section. To verify accuracy of posture detection algorithm we compare the transitions reported by the program with actual transitions from the protocol and absolute positions and timing recorded using the Vicon system. We found that the proposed algorithm performs flawlessly recognizing correctly all the sit-to-stand and stand-to-sit transitions.

Table 1 shows the average and the standard deviation of a subset of the parameters characterizing dynamic heart response to the sit-to-stand transitions in the protocol for all subjects. The total averages and standards deviation for all subjects are as follow: $T_{Transition}=2.7\pm 0.69$ s, $HR_{diff}=27.36\pm 9.30$ bpm, $HR_b=63.30\pm 9.02$ bpm, $HR_a=90.66\pm 10.09$ bpm. The results show a significant change of the heart rate (HR_{diff}) for each subject indicating potential of the proposed parameters in characterization sit-to-stand transition.

Table 1. The average and the standard deviation of a subset of the parameters characterizing the dynamic heart response to sit-to-stand transitions for 7 subjects (S1-S7).

Subject	$T_{Transition}$ [s]	HR_b [bpm]	HR_{diff} [bpm]	T_{HRMAX} [s]
S1	2.97±0.46	66.25±5.36	36.75±5.01	11.90±2.39
S2	2.73±0.63	81.2±4.82	18.79±4.41	8.99±2.08
S3	2.32±0.48	59.18±5.55	37.23±5.44	13.64±2.46
S4	1.99±0.74	53.66±4.23	32.73±6.33	12.16±3.62
S5	2.57±0.43	58.78±0.69	25.00±4.48	13.05±2.49
S6	2.74±0.47	61.12±2.53	26.51±3.53	9.22±4.58
S7	3.61±0.50	62.90±1.73	14.48±3.66	14.01±2.58

This paper's contributions are as follows. First, we developed algorithms that reliably detect posture transitions by processing data from a single 3D accelerometer built-in in a commercially available physiological monitor. Next, we proposed a set of parameters for characterization of the dynamic heart response to sit-to-stand transitions, and developed algorithms for their extraction. Finally, we implemented and successfully tested the *imWell* system on seven participants during structured experiments.

Whereas the goal of this paper was to develop the enabling technology for unobtrusive capturing of the heart dynamic response to posture transitions, further research is needed to develop methods to assess cardiac status and fitness using the proposed parameters and to provide feedback and guidance to the users.

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