# IMPROVING ABDOMEN TUMOR LOW-DOSE CT IMAGES USING DICTIONARY LEARNING BASED PATCH PROCESSING AND UNSHARP FILTERING

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# ABSTRACT

Reducing patient radiation dose, while maintaining a highquality image, is a major challenge in Computed Tomography (CT). The purpose of this work is to improve abdomen tumor low-dose CT (LDCT) image quality by using a two-step strategy: a first patch-wise non linear processing is first applied to suppress the noise and artifacts, that is based on a sparsity prior in term of a learned dictionary, then an unsharp filtering aiming to enhance the contrast of tissues and compensate the contrast loss caused by the DL processing. Preliminary results show that the proposed method is effective in suppressing mottled noise as well as improving tumor detectability.

*Index Terms*—Low-dose CT (LDCT), abdomen tumor, dictionary learning

## **1. INTRODUCTION**

CT imaging is increasingly incorporated into clinical decision making and despite rapid progresses in CT technology over the past decade, one major concern appears today related to the associated radiation rate rising [1-2]. A large number of researches in CT have been motivated by the need to reduce patient radiation dose. Among the possible solutions, the most straightforward one is to consider lowering the X-ray tube current. Nevertheless, lowdose CT provides degraded images by increased mottled noise and different kinds of non stationary artifacts [3-4], which render the interpretation of these images particularly difficult. Tumor tissues often thus appear under the form of mosaic shapes with a low contrasted illustration [5-6]. Two kinds of methods are applied to enhance image quality. They, either, directly proceed in the reconstruction domain or within a post-processing denoising stage. In both cases, efficient noise suppression and tumor tissue preservation remain challenging. Neighborhood filters have shown interesting properties for the restoration of noisy low dose CT images. Let cite for instance, adaptive filters [6] that

allow to reduce the X-ray dose by 50% for the same image quality and without loss in low contrast detectability. Other filters such as multiscale penalized weighted least-squares [7], bilateral filters [8] and Non Local Mean (LNLM) [9] have also shown some efficiency in enhancing anatomical/ pathological features in Low dose CT images.

Recent years have reported a growing interest in the study of sparse representation based dictionary learning (DL) and patch processing [10-16]. Compared to pixel-wise intensity update-based restoration methods, patch-wise DL processing are considered as being more robust to mottled noise and generally provides a more efficient representation of patch-shaped features such as tumors or organs. We describe in this paper, a new patch-wise processing, based on a sparsity prior in terms of a learned dictionary to suppress mottled noises in abdomen tumor LDCT images and a contrast-enhancing unsharp filter whose role is to compensate the contrast loss induced by the DL process. This method referred as **DL-unsharp** algorithm, is described in section 2. The flowchart of the method is given in Fig. 1. Section 3 provides a comparative study between our algorithm and a LNLM restoration filter [9]. Preliminary results show that the proposed DL-unsharp algorithm provides a good restoration of structures in LDCT images with an image quality that is comparable to the original standard-dose CT (SDCT) images.

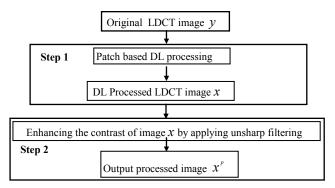


Fig. 1 Outline of the proposed DL-unsharp algorithm.

## 2. METHOD

The core idea is to impose a sparsity prior patch-wise on the LDCT images in terms of a *dictionary* D. Assuming the patches in the LDCT image are sparsely representable, DL based patch processing is carried out by coding each patch as a linear combination of just a few patches in the dictionary i.e. each patch of the image can be approximated by a linear combination of just a few columns from D [11-12]. This way to proceed leads to find the best global overcomplete dictionary. The coefficients of the linear combination can be estimated through the sparse coding process described in [13]. The DL based patch processing aims to solve the following optimization problem [14]:

$$\min_{x,D,\alpha} \|x - y\|_{2}^{2} + \mu \sum_{ij} \|R_{ij}x - D\alpha_{ij}\|_{2}^{2} \quad \text{s.t.} \quad \|\alpha_{ij}\|_{0}^{0} \le T \quad \forall i, j \quad (1)$$

where, *x* and *y* denote the treated and original LDCT images, respectively.  $R_{ij}$  is the operator that extracts the square patch  $x_{ij}$  of size  $\sqrt{n} \times \sqrt{n}$  (centered at point (i, j)) from the image *x*. This patch is encoded by  $D\alpha_{ij}$ . *D* is a  $n \times K$  matrix, which is composed by *K* columns of *n*-vectors. Each *n*vector column corresponds to a patch of size  $\sqrt{n} \times \sqrt{n}$ . Here  $\alpha$  includes all the coefficient set  $\{\alpha_{ij}\}$  for the sparse representation of all patches.  $\|\alpha_{ij}\|_{0}^{0}$  denotes the  $L_{0}$  norm that counts the nonzero entries of vector  $\alpha_{ij}$ , and *T* is the preset parameter of sparsity level that limits the maximum nonzero entry number in  $\alpha_{ij}$ .

The numerical solution of the optimization problem (1) is obtained by a weighted version of the K-means Singular Value Decomposition (K-SVD) algorithm [14]. It consists of two main steps:

$$\min_{D,\alpha} \sum_{ij} \left\| R_{ij} x - D\alpha_{ij} \right\|_{2}^{2} \quad \text{s.t.} \quad \left\| \alpha_{ij} \right\|_{0}^{0} \le T \quad \forall i, j$$

$$\min_{x} \|x - y\|_{2}^{2} + \mu \sum_{ij} \|R_{ij}x - D\alpha_{ij}\|_{2}^{2}$$
(3)

(2) aims to train the dictionary *D* and  $\alpha$  from a set of image patches. It is solved with the K-SVD after replacing *x* by the known observed image *y*. This operation is iteratively performed in two steps: (1) sparse coding of  $\alpha$  (including all  $\{\alpha_{ij}\}$ ) using the orthogonal marching pursuit (OMP) algorithm; (2) dictionary update by minimizing (2) with *D* being a matrix with unit-norm columns in order to avoid scaling ambiguity. Then with dictionary *D* available, we fix *D* and calculate  $\alpha$  using the OMP algorithm. Finally, given *D* and  $\alpha$ , we compute the output image *x* by solving (3) according to a simple least squares approach:

$$x = \left(I + \mu \sum_{y} R_{y}^{T} R_{y}\right)^{-1} \left(y + \mu \sum_{y} R_{y}^{T} D\alpha_{y}\right)$$
(4)

Contrary to what was pointed out in the literature, we

found that the dictionary trained from a SDCT abdomen image always provided results that were visually close to LDCT images (when compared with the dictionary trained from the LDCT image itself). The reason is that most abdomen CT images have similar tissue compositions and the dictionary discrepancy often expresses a very few difference in the final sparsified features. So we decided to use a pre-computed global dictionary  $D_p$  (cf. Fig.2 (a) for illustration) that was preliminarily trained from a high quality SDCT image (Fig.2 (b)). One advantage of using this global dictionary is that the intensive computations, involved in the dictionary construction, can be avoided.

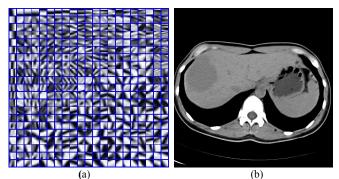


Fig. 2 (a) Dictionary example; (b) Abdomen SDCT image from which the dictionary has been trained.

We finally perform the optimization process using the global dictionary  $D_p$  obtained from (2) and consider the following three steps (S1)-(S3):

(S1), 
$$\min_{\alpha} \sum_{ij} \left\| \alpha_{ij} \right\|_{0}^{0} \text{ s.t. } \left\| R_{ij} \mathbf{x} - D_{p} \alpha_{ij} \right\|_{2}^{2} \le \varepsilon \ \forall i, j$$
(5)

(S2), 
$$\min_{x} \|x - y\|_{2}^{2} + \mu \sum_{ij} \|R_{ij}x - D_{p}\alpha_{ij}\|_{2}^{2}$$
(6)

(S3), 
$$x^{\nu} = \text{unsharpFilter}(x,\kappa)$$
 (7)

Here, the sparse coefficient  $\alpha$  and image *x* can be calculated by solving (5) and (6) using OMP and the least square approach. The  $\varepsilon$  in (5) denotes the tolerance parameter used in the computation of the sparse coefficients. Step S3 (7) characterizes the final contrast enhancing unsharp filtering with the  $\kappa$ -weight kernel [16]:

- K	- K	- K
<b>-</b> K	1+8 к	<b>-</b> K
- K	- K	<b>-</b> K

# **3. EXPERIMENT**

Approval of this study was granted by our institutional review board. A non-conflict of interest for this work was declared. SDCT images of abdomen were acquired on a multi-detector row Siemens Somatom Sensation 16 CT scanner with a tube current of 260mAs while LDCT images were obtained from a reduced tube current of 50 mAs. Considering the linear relationship between rube currents and X-ray dose, the radiation exposure in LDCT scan is less than 20% of the HDCT scan. The scanning parameters were the following: kVp, 120; slice thickness, 5 mm; Gantry rotation time, 0.5s; detector configuration (detector rows × section thickness), 16mm×1.5mm; table feed per gantry rotation, 24 mm; pitch, 1:1; reconstruction method: FBP algorithm with convolution kernel "B20f" ("B20f" is the routine smoothing kernel used in abdomen scans for Siemens CT). The windows and level setting were chosen to optimize the visualization of these data (center, 50HU; width, 350HU). For evaluation purpose, we compared the proposed method with the LNLM method in [9]. The LNLM method was accelerated using GPU (Graphics Processing Unit) techniques based on [9]. All the CT images were exported as DICOM files and then processed offline on a PC workstation (Intel Core<sup>™</sup> 2 Ouad CPU and 4096 Mb RAM, GPU (NVIDIA GTX465)) using Visual C++ as programming language (Visual Studio 2008 software; Microsoft).

For both algorithms, the parameter setting was completed applying a greedy algorithm to find the optimal parameter that provided the best qualitative results. This qualitative evaluation was carried out in collaboration with a radiologist (X. D.Y, 15 years clinical experience). These optimal parameters are listed in TABLE I with the computation time costs for each method.

 TABLE I.

 PARAMETER SETTING AND COMPUTATION COST (IN SECONDS) FOR

 DIFFERENT METHODS

	LNLM method	DL-unsharp method			
Parameter setting	h = 2, Patch size $Np = 7 \times 7$ , Neighborhood size $Nn = 81 \times 81$	K=256, Np=8×8, $L_0$ =3, Iteration=20, T=21, $\varepsilon$ =21, $\mu$ =0.5 Unsharp filter: $\kappa$ =0.1,			
Computation		K-step	O-step	I-step	F-step
Cost (in seconds)	8.07	979.53	2.28	0.96	0.12

To specify the computation cost for different steps in the proposed DL-unsharp processing, we use K-step, O-step, I-step and F-step to represent the K-SVD step (2)-(3) (dictionary training), OMP step (5) (sparse coefficient estimation), the image update step (6), and the unsharp filtering step (7), respectively. We see in TABLE I that the dictionary learning in the K-step method is computationally much more time consuming than the following steps. So, if we remove the K-step and replace it by a pre-trained global dictionary (Fig.3 (a)), the proposed implementation (2.28 +0.96 +0.12 = 3.36 seconds) becomes much more computationally efficient than the LNLM method (8.07 seconds).

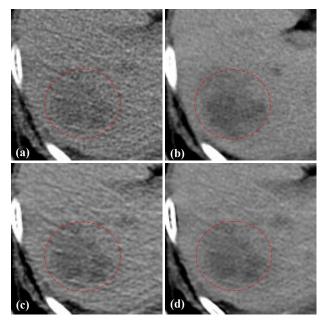


Fig.3 Results for a dataset of a 61 years female patient having a liver tumor (red circles). (a) Original LDCT image; (b) Original SDCT image; (c) LNLM processed LDCT image; (d) DL-unsharp processed LDCT image.

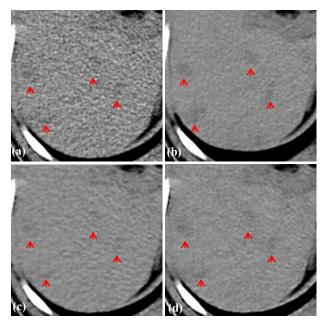


Fig.4 Results for a dataset of one 56 years male patient having multiple hepatic metastases (red arrows) in the abdomen. (a) Original LDCT image; (b) Original SDCT image; (c) LNLM processed LDCT image; (d) DL-unsharp processed LDCT image.

Fig.3 and 4 illustrate the results for two patient datasets. Fig.3 (a) and Fig.4 (a) depict two abdomen LDCT images including tumors (specified by red circles or arrows) of a 61 years old female and 56 years old male patient, respectively. Fig.3 and Fig.4 (b), (c) and (d) show the corresponding SDCT, LNLM processed LDCT and DL-unsharp processed LDCT images respectively. We observe that, under low dose scanning condition, mottled noise severely degrades the images and the tumor boundary appears obscured. Considering the SDCT images as references, we observe that the LNLM processed images (Fig. 3 (c) and Fig. 4 (c)) have been smoothed but still contain noise and stripe artifacts. The result appears more convincing with the DL-unsharp method since we can observe a more efficient noise reduction with a good preservation of tumor structures (Fig. 3 (d) and Fig. 4 (d)). Their restoration provides texture appearances close to those of the original SDCT images. In the one including multiple hepatic metastases in Fig. 4, the DL-unsharp algorithm allows enhancing the small structures as the small lesions which appears better discriminated than in the LNLM processed images (see arrows).

#### 4. CONCLUSION

The algorithm described here and named DL-unsharp is employed for improving abdomen LDCT image quality, the objective being both to suppress the mottled noise and streak artifacts while enhancing the structure edges especially on tumors or lesions. This method makes use of a patch based DL processing followed by a contrast restoration unsharp filtering. Furthermore, the dictionary training can be built from available abdomen SDCT images to optimize the algorithm performance. We demonstrated the potential of the proposed approach on abdomen tumor LDCT datasets. Experiment results showed the proposed approach can greatly improve the quality of images with an over 80% reduced X-ray dose.

However, some improvements are still needed: First, the whole computation cost of the DL-unsharp processing still need to be accelerated to meet the clinical requirement (often less than 1 second per image). Second, some parameters are currently set empirically and need more experiments to validate their value. Thirdly, extensive experiments with large image samples have to be led to confirm these preliminary results. In conclusion, future work will be devoted to all these points: parallelization of involved pair-wise operations, automatic estimation of the best parameters to optimize the DL-unsharp processing, and exploring the proposed application in processing other LDCT images.

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