# **Study of Magnetization Evolution by Using Composite Spin-lock Pulses for T1ρ Imaging**

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*Abstract***— B<sup>0</sup> and B<sup>1</sup> field inhomogeneities may generate banding-like artifacts in T1ρ-weighted images and hence result in errors of T1ρ quantification. Several types of composite spin-lock pulses have been proposed to alleviate such artifacts. In this study, magnetization evolution with**  $T_{1\rho}$  **and**  $T_{2\rho}$  **relaxation by using these composite spin-lock pulses are theoretically derived. The effectiveness and limitation of each spin-lock pulse are explicitly illustrated in mathematical forms and phantom T1ρ-weighted images acquired by using each spin-lock pulse are presented. This study also provides a theoretical framework for T**<sub>**1**</sub>**Quantification from T**<sub>1</sub> $\rho$ -weighted images even with  $B_0$  and  $B_1$ **inhomogeneity artifacts.**

#### I. INTRODUCTION

 $T_{1\rho}$  is the time constant of the transverse magnetization decay given the application of a spin-lock pulse, which is aligned with the net magnetization vector.  $T_{10}$  relaxation is able to create tissue contrast different from the conventional MRI contrasts based on  $T_1$  and  $T_2$  relaxation.  $T_{1\rho}$  relaxation contrast is sensitive to low frequency motional processes, and is potential for many clinical applications [1-6].

Conventionally, a three-pulse cluster including tip-down, spin-lock and tip-up pulse is used to generate  $T_{1\rho}$ -weighted images. However, in the presence of inhomogeneous  $B_0$  and  $B_1$  field, the net magnetization may not align with the spin-lock field any longer, and accordingly result in a complicated magnetization evolution and hence banding-like artifact on  $T_{10}$ -weighted images. Composite spin-lock pulses have been proposed to reduce the artifacts. In this paper, we present a review of several types of composite spin-lock pulses and the magnetization evolutions with  $T_{10}$  and  $T_{20}$ relaxation by using each spin-lock pulse are theoretically derived. The relationship between the magnetization and various factors of spin-lock time, spin-lock frequencies,  $B_0$ and  $B_1$  inhomogeneities are illustrated.

## II. THEORY

## *A. Conventional spin-lock pulse: 90x-TSLy-90-x*

A conventional spin-lock pulse (Fig. 1) consists of three pulses: an initial hard pulse along x direction to tip-down the net magnetization to the transverse plane, a hard spin-lock pulse with duration of TSL to excite  $T_{1\rho}$  relaxation, and a final

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hard pulse along  $-x$  direction to tip-up the net magnetization from the transverse plane to the longitudinal plane. Principally, the magnetization aligned with the spin-lock field decays with  $T_{10}$  and the magnetization perpendicular to the spin-lock field decays with  $T_{2p}$ .



Figure 1. The schematic of conventional spin-lock pulse.

The magnetization evolution during the application of a pulse can be traced by using the Block Equation. For description, an RF pulse is represented in the form of matrix notation  $R_{\varphi}(\Phi)$ , where *R* denotes a rotation matrix,  $\varphi$  is the pulse orientation and  $\Phi$  is the pulse flip angle.  $\beta$  is the flip angle of tip-down/tip-up pulse and  $\partial$  is the flip angle of each SL segment. Given spin-lock frequency FSL, *∂=2π∙FSL∙TSL*.  $E_\rho$  is a matrix to describe T<sub>1p</sub> and T<sub>2p</sub> relaxation. The basic rotation matrices that rotate spin vectors about the x, y, or z axis by an angle  $\Phi$  in three dimensions, and  $E_\rho$  are expressed as in Equation (1),

$$
R_{x}(\Phi) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\Phi & \sin\Phi \\ 0 & -\sin\Phi & \cos\Phi \end{bmatrix}; R_{y}(\Phi) = \begin{bmatrix} \cos\Phi & 0 & -\sin\Phi \\ 0 & 1 & 0 \\ \sin\Phi & 0 & \cos\Phi \end{bmatrix};
$$
  

$$
R_{z}(\Phi) = \begin{bmatrix} \cos\Phi & \sin\Phi & 0 \\ -\sin\Phi & \cos\Phi & 0 \\ 0 & 0 & 1 \end{bmatrix}; E_{\rho} = \begin{bmatrix} e^{-\frac{TSL}{2T_{z_{\rho}}}} & 0 & 0 \\ 0 & e^{-\frac{TSL}{2T_{z_{\rho}}}} & 0 \\ 0 & 0 & e^{-\frac{TSL}{2T_{z_{\rho}}}} \end{bmatrix}
$$
 (1)

The relaxation during P1 and P2 is usually negligible due to their much shorter pulse duration than the TSL. The magnetization evolution is expressed as in Equation (2),

$$
M(t) = R_{-x}(\beta) \cdot R_{y}(\partial) E_{\rho} \cdot R_{x}(\beta) \cdot M(t_{0})
$$
  
\n
$$
\Rightarrow M_{z} = M_{0} \cdot (\sin^{2} \beta \cdot e^{-TSL/T_{1}\rho} + \cos^{2} \beta \cos \partial \cdot e^{-TSL/T_{2}\rho})
$$
 (2)

Where  $M(t_0) = [0 \ 0 \ M_0]$ '. When the tip-down/tip-up pulse has a perfect flip angle of  $90^\circ$ , the resulting longitudinal magnetization is simply related to  $T_{1\rho}$  relaxation as the normal mono-exponential relaxation model shown in Equation (3),

$$
M_z = M_0 \cdot e^{-T \Sigma L / T_1 \rho} \tag{3}
$$

Given imperfect tip-down/tip-up flip angles, a magnetization precession around the spin-lock field occurs (Fig. 2). A flip angle of ∂ is formed as the magnetization precesses from point 1 to point 2 during TSL. As a result, this pulse is  $B_1$  sensitive as  $\partial$  is related to B<sub>1</sub>.

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Figure 2. Magnetization precession of conventional spin-lock pulse.

## *B. Rotary-echo spin-lock pulse: 90x-TSL/2y- TSL/2-y -90-x*

This pulse divides a spin-lock pulse into two segments which have opposite phase shifts (Fig. 3) and tends to remove the artifact resulted from the flip angle of SL pulse  $\partial$  [7]. During SL1, the magnetization M precesses from point 1 to point 2 with flip angle of ∂ and then precesses from point 2 to point 3 during SL2 (Fig. 4). Given the same duration of SL1 and SL2, point 3 is identical as point 1. The resulting longitudinal magnetization will be irrelevant with ∂. The magnetization evolution is expressed as in Equation (4),

$$
M(t) = R_{-x}(\beta) \cdot R_{-y}(\partial) E_{\rho} \cdot R_{y}(\partial) E_{\rho} \cdot R_{x}(\beta) \cdot M(t_0)
$$
  
\n
$$
\Rightarrow M_{z} = M_0 \cdot (\sin^2 \beta \cdot e^{-TSL/T_1\rho} + \cos^2 \beta \cdot e^{-TSL/T_2\rho})
$$
\n(4)

When tip-down/tip-up flip angle equals to  $90^\circ$ , the resulting longitudinal magnetization is simplified as Equation (3). Note that image could still be contaminated by  $T_{2\rho}$  contrast in the presence of  $B_1$  field inhomogeneity according to Equation (4)  $\frac{1}{2}$  when β≠90°.



Figure 3. The schematic of rotary-echo spin-lock pulse.



Figure 4. Magnetization precession of rotary-echo spin-lock pulse.

Equation (4) is derived with the assumption of homogeneous  $B_0$ . When there is an offset of  $\Delta B_0$ , the effective spin-lock field will change to *z'* and *z''* given the application of SL1 and SL2 respectively (Fig. 5), where *θ*=*tan<sup>-1</sup>*(*ω*<sub>*1*</sub>/∆*ω*)=*tan<sup>-1</sup>*(*B*<sub>*1*</sub>/ $\overline{AB}$ <sub>*0*</sub>) is the angle from the effective spin-lock field to z-axis. M precesses initially from point 1 to point 2 during SL1 and then precesses from point 2 to point 3

during SL2. The magnetization evolution becomes much more complicated as shown in Equation (5).

$$
M(t) = R_{-x}(\beta) \cdot R_{z}(\partial) E_{\rho} \cdot R_{z}(\partial) E_{\rho} \cdot R_{x}(\beta) \cdot M(t_{0})
$$
  
\n=  $R_{-x}(\beta) \cdot R_{x}(-\theta) R_{z}(\partial) E_{\rho} R_{x}(\theta) \cdot R_{x}(\theta) R_{z}(\partial) E_{\rho} R_{x}(-\theta) \cdot R_{x}(\beta) \cdot M(t_{0})$   
\n $\Rightarrow M_{z} = M_{0} \cdot [\cos 2\theta(\cos^{2} \beta - \sin^{2} \theta) \cdot e^{-TSL/T_{1\rho}}$   
\n $+ (\cos^{2} \beta - \cos^{2} \theta)(\sin^{2} \partial - \cos^{2} \partial \cos 2\theta) \cdot e^{-TSL/T_{2\rho}}$   
\n $+ \cos \partial \sin^{2} 2\theta \cdot e^{-0.5TSL/T_{1\rho}} \cdot e^{-0.5TSL/T_{2\rho}}$ 

(5)



Figure 5. Magnetization precession of rotary-echo spin-lock pulse in inhomogeneous B<sub>0</sub> field.

If  $ω_1$ > $\triangle$ Δω,  $θ=90^\circ$ , Equation (5) is identical as Equation (4). If  $\omega_1$  << $\Delta \omega$ ,  $\theta$ = $0^\circ$ , Equation (5) is simplified as shown in Equation (6),

$$
M_z = M_0 \cdot [\cos^2 \beta \cdot e^{-TSL/T_{1\rho}} + \sin^2 \beta \cos(2\hat{\sigma}) \cdot e^{-TSL/T_{2\rho}}]
$$
 (6)  
When  $\beta$ =90°, trace of T<sub>1\rho</sub> relaxation will be lost and only T<sub>2\rho</sub>  
relaxation can be traced by Equation (6).

If  $ω_1~Δω$  and  $β=90°$ , Equation (5) is simplified as shown in Equation (7) and artifacts will be serious [8],

$$
M_z = M_0 \cdot [-\cos 2\theta \sin^2 \theta \cdot e^{-T S L/T_{1\rho}}- \cos^2 \theta (\sin^2 \theta - \cos^2 \theta \cos 2\theta) \cdot e^{-T S L/T_{2\rho}}+ \cos \theta \sin^2 2\theta \cdot e^{-0.5 T S L/T_{1\rho}} \cdot e^{-0.5 T S L/T_{2\rho}}]
$$
(7)

# *C. B<sup>1</sup> and B<sup>0</sup> insensitive composite spin-lock pulse: 90x-TSL/2y- 180y- TSL/2-y -90-x*

This spin-lock pulse inserts a refocusing pulse between rotary-echo spin-lock pulse segments (Fig. 6) so as to cancel the flip angle of spin-lock pulse in imperfect  $B_0$  field [9]. During SL1, M precesses from point 1 to point 2 and then is reversed by the refocusing pulse, precessing 180° around y-axis to point 3. During SL2, M precesses from point 3 to point 4 which is identical as point 1. Hence, the resulting magnetization is irrelevant with ∂. The magnetization evolution is expressed as in Equation (8),

$$
M(t) = R_{-x}(\beta) \cdot R_z(\partial) E_{\rho} \cdot R_y(2\beta) \cdot R_z(\partial) E_{\rho} \cdot R_x(\beta) \cdot M(t_0)
$$
  
\n=  $R_{-x}(\beta) \cdot R_x(-\theta) R_z(\partial) E_{\rho} R_x(\theta) \cdot R_y(2\beta) \cdot R_x(\theta) R_z(\partial) E_{\rho} R_x(-\theta) \cdot R_x(\beta) \cdot M(t_0)$   
\n $\Rightarrow M_z = M_0 \cdot [e^{-TSL/T_{\rho}} \cdot (\cos^2 \beta - \sin^2 \theta)(\cos^2 \theta \cos 2\beta - \sin^2 \theta)$   
\n+  $e^{-TSL/T_{2\rho}} \cdot (\cos^2 \beta - \cos^2 \theta)$   
\n $\cdot (-\cos^2 \partial \cos^2 \theta + \cos(2\beta) \sin^2 \partial + \cos(2\beta) \cos^2 \partial \sin^2 \theta)$   
\n+  $\frac{1}{2} e^{-0.5TSL/T_{1\rho}} e^{-0.5TSL/T_{2\rho}} \cdot (1 + \cos(2\beta))$ 

 $\cdot$  (cos $\partial$ sin<sup>2</sup>(2 $\theta$ ) + 2sin  $\partial$ cos $\theta$  – 2cos(2 $\beta$ )sin  $\partial$ cos $\theta$ )]

(8)



Figure 6. The schematic of  $B_1$  and  $B_0$  insensitive composite spin-lock pulse.

If  $\beta$ =90°, Equation (8) is simplified as Equation (9),

$$
M_z = M_0 (\sin^2 \theta \cdot e^{-T S L / T_{1\rho}} + \cos^2 \theta \cdot e^{-T S L / T_{2\rho}})
$$
\n(9)

The resulting longitudinal magnetization will be irrelevant with  $\partial$ . If  $\omega_1$ > $\Delta \omega$ ,  $\theta = 90^\circ$ , Equation (9) is simplified as Equation (3). If  $\omega_1 \ll \Delta \omega$ ,  $\theta = 0^\circ$ , Equation (9) is simplified as Equation (10) which is a mono-exponential  $T_{2\rho}$  relaxation model,

$$
M_z = M_0 \cdot e^{-T S L / T_{2\rho}} \tag{10}
$$

If  $\beta \neq 90^\circ$ , provided  $\omega_1 >> \Delta \omega$ ,  $\theta = 90^\circ$  and  $\omega_1 << \Delta \omega$ ,  $\theta = 0^\circ$ , Equation (10) is simplified as Equation (11) and (12) respectively and artifacts will occur.

$$
M_z = M_0 \cdot [e^{-T S L/T_{1\rho}} \cdot \sin^2 \beta + e^{-T S L/T_{2\rho}} \cdot \cos^2 \beta \cos(2\beta)] \quad (11)
$$
  
\n
$$
M_z = M_0 \cdot [e^{-T S L/T_{1\rho}} \cdot \cos^2 \beta \cos(2\beta) + e^{-T S L/T_{2\rho}} \cdot \sin^2 \beta (\cos^2 \partial - \sin^2 \partial \cos(2\beta)) + e^{-0.5 T S L/T_{1\rho}} e^{-0.5 T S L/T_{2\rho}} \cdot \sin^2(2\beta) \sin \partial] \quad (12)
$$



Figure 7. Magnetization precession of  $B_1$  and  $B_0$  insensitive composite spin-lock pulse.

# *D. Revised B<sup>1</sup> and B<sup>0</sup> insensitive composite spin-lock pulse: 90x-TSL/2y- 180y- TSL/2-y -90<sup>x</sup>*

As shown in Section II.C,  $B_1$  and  $B_0$  insensitive composite spin-lock pulse loses its effectiveness when  $\beta$  is not  $90^{\circ}$ . The revised composite spin-lock pulse is robust for imperfect tip-down/tip-up flip angle [10]. The last tip-up pulse is modified to be aligned with x-axis (Fig. 8) and tips the magnetization to –z-axis. Given imperfect tip-down/tip-up flip angle, M precesses around *z'* from point 1 to point 2 during SL1 and then precesses from point 2 to point 3 with the function of refocusing pulse. During SL2, M precesses from point 3 to point 4 around *z''*. Point 4 and point 1 should be symmetric about y-axis. Lastly, with the tip-up pulse, M will perfectly return to –z-axis. The process can remove the contaminations from imperfect tip-down/tip-up flip angle, while  $180^\circ$  flip angle of refocusing pulse is still necessary. Supposing  $\delta$  is the flip angle of refocusing pulse, the magnetization evolution is expressed as in Equation (13),

$$
M(t) = R_x(\beta) \cdot R_z(\partial) E_{\rho} \cdot R_y(\delta) \cdot R_z(\partial) E_{\rho} \cdot R_x(\beta) \cdot M(t_0)
$$
  
\n=  $R_x(\beta) \cdot R_x(-\theta) R_z(\partial) E_{\rho} R_x(\theta) \cdot R_y(\delta) \cdot R_x(\theta) R_z(\partial) E_{\rho} R_x(-\theta) \cdot R_x(\beta) \cdot M(t_0)$   
\n $\Rightarrow M_z = M_0 \cdot [e^{-TSL/T_{z\rho}} \cdot \cos^2(\beta - \theta)(\cos\delta\cos^2\theta - \sin^2\theta)$   
\n+  $e^{-TSL/T_{z\rho}} \cdot \sin^2(\beta - \theta)(-\cos^2\theta\cos^2\theta + \cos\delta\sin^2\theta + \cos\delta\cos^2\theta\sin^2\theta)$   
\n+  $\frac{1}{2}e^{-0.5TSL/T_{z\rho}}e^{-0.5TSL/T_{z\rho}} \cdot (1 + \cos\delta)\cos\delta\cos\delta\sin(2\theta)(\sin(2\theta) - \cos(2\theta))]$   
\n(13)



Figure 8. The schematic of revised  $B_1$  and  $B_0$  insensitive composite spin-lock pulse.



Figure 9. Magnetization precession of revised  $B_1$  and  $B_0$  insensitive composite spin-lock pulse.

If  $\delta$ =180°, Equation (13) is simplified as Equation (14),

$$
M_z = -M_0 \cdot [e^{-T S L/T_{1\rho}} \cdot \cos^2(\beta - \theta) + e^{-T S L/T_{2\rho}} \cdot \sin^2(\beta - \theta)] \tag{14}
$$

M returns to –z-axis, with the contamination from  $T_{2\rho}$ relaxation.

If  $\delta \neq 180^\circ$ , provided  $\omega_1 \geq \Delta \omega$ ,  $\theta = 90^\circ$  and  $\omega_1 \leq \Delta \omega$ ,  $\theta = 0^\circ$ , Equation (13) is simplified as Equation (15) and Equation (16) respectively and artifacts will occur.

$$
M_z = M_0 \left( -e^{-TSL/T_{1\rho}} \cdot \sin^2 \beta + e^{-TSL/T_{2\rho}} \cdot \cos^2 \beta \cos \delta \right)
$$
\n
$$
M_z = M_0 \left[ e^{-TSL/T_{1\rho}} \cdot \cos^2 \beta \cos \delta - e^{-TSL/T_{2\rho}} \cdot \sin^2 \beta (\cos^2 \beta - \cos \delta \sin^2 \beta) \right]
$$
\n
$$
(16)
$$

#### III. IMAGING EXPERIMENT

The rotary-echo spin-lock pulse (SL pulse B),  $B_1$  and  $B_0$ insensitive composite spin-lock pulse (SL pulse C) and revised  $B_1$  and  $B_0$  insensitive composite spin-lock pulse (SL pulse D) were experimentally tested. Each spin-lock pulse was implemented with Turbo spin-echo (TSE) sequence on a 3T MRI scanner (Philips Medical Systems, Best, The Netherlands). A homogeneous agar phantom was imaged. Body coil was used for excitation so homogeneous B1 field was assumed. A birdcage head coil was used as a receiver. The parameters were set as following: FSL = 50, 250 and 500Hz; TSL = 20ms; TR/TE =  $4000/17$ ms; image matrix size = 144×144; FOV =  $20 \text{cm}^2$ ; slice thickness = 8mm; echo train length = 6; BW = 217Hz/pixel. An interval of 5000ms was inserted after each shot to allow fully recovery of longitudinal magnetization. Fig. 10 presents the  $B_0$  map acquired by the normal dual-TE method (ΔTE=1ms) imaging results. SL pulse C and D are obviously less sensitive to  $B_0$  inhomogeneity.



Figure 10.  $T_{1\rho}$  weighted images obtained by using SL pulse B, C, D respectively.

## IV. DISCUSSION

As identified from the magnetization evolution and imaging results of the investigated spin-lock pulses, imperfect flip angle of tip-down/tip-up/refocus pulse due to inhomogeneous  $B_1$  field will complicate the orientation of the net magnetization. The deviation of the effective spin-lock field from the nominal spin-lock field due to inhomogeneous  $B<sub>0</sub>$  further complicates the magnetization evolution and leads to signal null (banding artifact) and/or signal contamination from  $T_{20}$  relaxation.

Although composite spin-lock pulses can be used to reduce the spin-lock artifacts associated with  $B_0$  and  $B_1$  field imperfections to different extents, complete elimination of such artifacts is still technically challenging in practice.

Improvement of  $T_{1\rho}$  quantification can be realized either by reducing artifacts from  $T_{1\rho}$ -weighted images and then following the simple mono-exponential relaxation model for fitting, or by fitting the signal intensity of  $T_{10}$ -weighted images even with artifacts to a more complicated magnetization model which is able to quantify  $T_{1\rho}$  and  $T_{2\rho}$  relaxation even in the presence of field imperfections, as demonstrated in the literature [8]. The former one works at an image acquisition stage; the latter one works at an image post-processing stage. Our study provides a theoretical framework beneficial for both.

This study has some limitations. Phase cycling technique [11] was not analyzed in this study. The theoretical derivation does not account for the transient effect during the spin-lock time. The transient effect may partially explain the incomplete banding compensation by composite spin-lock pulses, in particular for tissues with short  $T_1$  relaxation time. Besides, the phantom imaging demonstration in this study is rather qualitative without taking  $B_1$  inhomogeneities into account. Quantitative evaluation and *in vivo* validation should be further performed in the future studies.

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